# Transversal and cotransversal matroids via their representations.

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#### Abstract.

It is known that the duals of transversal matroids are precisely the strict gammoids. We show that, by representing these two families of matroids geometrically, one obtains a simple proof of their duality.

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This note gives a new proof of the theorem, due to Ingleton and Piff [3], that the duals of transversal matroids are precisely the strict gammoids. Section 1 defines the relevant objects. Section 2 presents explicit representations of the families of transversal matroids and strict gammoids. Section 3 uses these representations to prove the duality of these two families.

## 1

**Matroids and duality.** A matroid  $M = (E, \mathcal{B})$  is a finite set E, together with a non-empty collection  $\mathcal{B}$  of subsets of E, called the *bases* of M, which satisfy the following axiom: If  $B_1, B_2$  are bases and e is in  $B_1 - B_2$ , there exists f in  $B_2 - B_1$  such that  $(B_1 - e) \cup f$  is a basis.

If  $M = (E, \mathcal{B})$  is a matroid, then  $\mathcal{B}^* = \{E - B \mid B \in \mathcal{B}\}$  is also the collection of bases of a matroid  $M^* = (E, \mathcal{B}^*)$ , called the *dual* of M.

**Representable matroids.** Matroids can be thought of as providing a combinatorial abstraction of linear independence. If V is a set of vectors in a vector space and  $\mathcal{B}$  is the

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collection of maximal linearly independent subsets of V, then  $M = (V, \mathcal{B})$  is a matroid. Such a matroid is called *representable*, and V is called a *representation* of M.

**Transversal matroids.** Let  $A_1, \ldots, A_r$  be subsets of  $[n] = \{1, \ldots, n\}$ . A transversal (or system of distinct representatives) of  $(A_1, \ldots, A_r)$  is an r-subset of [n] whose elements can be labelled  $\{e_1, \ldots, e_r\}$  in such a way that  $e_i$  is in  $A_i$  for each i. The transversals of  $(A_1, \ldots, A_r)$  are the bases of a matroid on [n].

Such a matroid is called a *transversal matroid*, and  $(A_1, \ldots, A_r)$  is called a *presentation* of the matroid. This presentation can be encoded in the bipartite graph H with "top" vertex set T = [n], "bottom" vertex set  $B = \{\widehat{1}, \ldots, \widehat{r}\}$ , and an edge joining j and  $\widehat{i}$  whenever j is in  $A_i$ . The transversals are the r-sets in T that can be matched to B. We will denote this transversal matroid by M[H].

**Strict gammoids.** Let G be a directed graph with vertex set [n], and let  $A = \{v_1, \ldots, v_r\}$  be a subset of [n]. We say that an r-subset B of [n] can be linked to A if there exist r vertex-disjoint directed paths, each of which has its initial vertex in B and its final vertex in A. Each individual path is allowed to have repeated vertices and edges. Such a collection of r paths is called a routing from B to A. The r-subsets which can be linked to A are the bases of a matroid denoted L(G, A). We can assume that the vertices in A are sinks of G; that is, that there are no edges coming out of them. This is because the removal of those edges does not affect the matroid L(G, A).

The matroids that arise in this way are called *strict gammoids* or *cotransversal matroids*. The purpose of this note is to give a new proof of the following theorem, due to Ingleton and Piff.

**Theorem 1.** [3] Strict gammoids are precisely the duals of transversal matroids.

### 2

Let  $\mathbb{K}$  be the field of fractions of the ring of formal power series in the indeterminates  $x_{ij}$  indexed by  $1 \leq i \leq r$  and  $1 \leq j \leq n$ . We now show how transversal matroids and strict gammoids can be represented over  $\mathbb{K}^{1}$ .

**A representation of transversal matroids.** Let M be a transversal matroid on the set [n] with presentation  $(A_1, \ldots, A_r)$ . Let X be the  $r \times n$  matrix whose (i, j) entry is  $-x_{ij}$  if  $j \in A_i$  and is 0 otherwise. The columns of X are a representation of M in the vector space  $\mathbb{K}^r$ . To see this, consider the columns  $j_1, \ldots, j_r$ . They are independent when their determinant is non-zero, and this happens as soon as one of the r! summands of the determinant is non-zero. But  $\pm X_{\sigma_1 j_1} \cdots X_{\sigma_r j_r}$  (where  $\sigma$  is a permutation of [r]) is non-zero if and only if  $j_1 \in A_{\sigma_1}, \ldots, j_r \in A_{\sigma_r}$ . So the determinant is non-zero if and only if  $j_1 \in A_{\sigma_1}, \ldots, j_r \in A_{\sigma_r}$ .

We will find it convenient to choose a transversal  $j_1 \in A_1, \ldots, j_r \in A_r$  at the outset, and normalize the rows to have the  $(i, j_i)$  entry be  $-x_{ij_i} = 1$  for  $1 \le i \le r$ .

<sup>&</sup>lt;sup>1</sup>It is possible to carry out the same constructions over  $\mathbb{R}$ , but special care is required to handle the issue of convergence of the infinite sums that will arise.

*Example 1.* Let n = 6 and  $A_1 = \{1, 2, 3\}, A_2 = \{2, 4, 5\}, A_3 = \{3, 5, 6\}$ . The corresponding bipartite graph H is shown below.



If we choose the transversal  $1 \in A_1, 2 \in A_2, 3 \in A_3$ , we obtain a representation for the transversal matroid M[H], given by the columns of the following matrix:

**A representation of strict gammoids.** Let M = L(G, A) be a strict gammoid. Say G has vertex set [n], and assume  $A = \{r + 1, \ldots, n\}$ . Any edge  $i \to j$  of G has  $i \leq r$ , so we can assign to it weight  $x_{ij}$ . Let the weight of a path in G be the product of the weights on its edges. For each vertex i of G and each sink a in A, let  $p_{ia}$  be the sum of the weights of all paths in G which start at vertex i and end at sink a. We allow paths with repeated vertices and edges in this sum, so there may be infinitely many such paths; however, the number of paths of a given weight is finite, so  $p_{ia}$  is a well-defined element of  $\mathbb{K}^2$ .

Let Y be the  $(n-r) \times n$  matrix whose (a, i) entry is  $p_{ia}$ . The columns of Y are a representation of M. To see this, recall the Lindström-Gessel-Viennot theorem, which states that the determinant of the submatrix with columns  $i_1, \ldots, i_{n-r}$  is equal to the signed sum of the weights of the routings from  $\{i_1, \ldots, i_{n-r}\}$  to A.<sup>3</sup>

Notice that two routings  $R_1$  and  $R_2$  having the same weight must have the same multiset of edges. They can only differ in the order in which the kth path of  $R_1$  and the kth path of  $R_2$  traverse the same multiset of edges, as they go from  $i_k$  to  $j_k$ . But then  $R_1$  and  $R_2$  will also have the same sign. We conclude that there is no cancellation in the signed sum under consideration. Therefore the determinant of the submatrix with columns  $i_1, \ldots, i_{n-r}$  is non-zero if and only if the signed sum is non-empty; that is, if and only if  $\{i_1, \ldots, i_{n-r}\}$  can be linked to A.

*Example 2.* Consider the directed graph G shown below, where all edges point down, and the set  $A = \{4, 5, 6\}$ .

<sup>&</sup>lt;sup>2</sup>In fact,  $p_{ia}$  is a rational function in the  $x_{ij}$ s. For a proof, see [10, Theorem 4.7.2].

<sup>&</sup>lt;sup>3</sup>If the kth path in a routing starts at  $i_k$  and ends at  $j_k$ , then the sign of the routing is the sign of the permutation  $j_1 \ldots j_{n-r}$  of A.



The representation we obtain for the strict gammoid L(G, A) is given by the columns of the following matrix:

**Representations of dual matroids.** If a rank-r matroid M is represented by the columns of an  $r \times n$  matrix A, we can think of M as being represented by the r-dimensional subspace V = rowspace(A) in  $\mathbb{K}^n$ . The reason is that, if we consider any other  $r \times n$  matrix A' with V = rowspace(A'), the columns of A' also represent M.

This point of view is very amenable to matroid duality. If M is represented by the r-dimensional subspace V of  $\mathbb{K}^n$ , then the dual matroid  $M^*$  is represented by the (n-r)-dimensional orthogonal complement  $V^{\perp}$  of  $\mathbb{K}^n$ .

Notice that the rowspaces of the matrices X and Y in the examples above are orthogonally complementary. That is, essentially, the punchline of this story.

# 3

**Directed graphs with sinks and bipartite graphs with complete matchings.** Given a directed graph G and a subset A of its set of sinks, we construct an undirected graph H as follows. We first split each vertex v not in A into a "top, incoming" vertex v and a "bottom, outgoing" vertex  $\hat{v}$ , and draw an edge between them. Then we replace each edge  $u \to v$  of G with an edge between the outgoing  $\hat{u}$  and the incoming v.

More concretely, given a directed graph G with vertex set V, and given a set A of sinks of G, we construct a bipartite graph H, together with a fixed bipartition and a fixed complete matching. The top vertex set in the bipartition is V, and the bottom vertex set is a copy  $\hat{V} - \hat{A}$  of V - A. The complete matching is obtained by joining the top u and the bottom  $\hat{u}$  for each u in V - A. Then, for  $u \neq v$ , we join the bottom  $\hat{u}$  and the top v in H if and only if  $u \to v$  is an edge of G.

Conversely, if we are given the bipartite graph H, a bipartition of  $H^4$  and a complete matching of H, it is clear how to recover G and A. The resulting G and A will depend on which bipartition and matching are used. Observe that if we start with the directed graph G and sinks A of Example 2, we obtain the bipartite graph H of Example 1.

<sup>&</sup>lt;sup>4</sup>which is unique if H is connected

Having laid the necessary groundwork, we can now present our proof of Theorem 1.

**Proof of Theorem 1: Duality of transversal matroids and strict gammoids.** We constructed a correspondence between a directed graph G with a specified subset A of its set of sinks, and a bipartite graph H with a specified bipartition and a specified complete matching. Now we show that, in this correspondence, the strict gammoid L(G, A) is dual to the transversal matroid M[H]. We have constructed a subspace of  $\mathbb{K}^n$  representing each one of them. By the remarks at the end of Section 2, it suffices to show that these two subspaces are orthogonally complementary, as observed in Examples 1 and 2.

Our representation of M[H] is given by the columns of the  $r \times n$  matrix X whose (i, i) entry is 1, and whose (i, j) entry, for  $i \neq j$ , is  $-x_{ij}$  if  $i \to j$  is an edge of G and is 0 otherwise. Think of the  $x_{ij}$ s as weights on the edges of G. For a vector  $y \in \mathbb{K}^n$ , the *i*th entry of the column vector Xy is  $y_i - \sum_{j \in N(i)} x_{ij}y_j$ , where the sum is over the set N(i) of vertices j such that  $i \to j$  is an edge of G. It follows that y is in the nullspace of X when, for each vertex i of G,

$$y_i = \sum_{j \in N(i)} x_{ij} y_j.$$

As before, let  $p_{ia}$  be the sum of the weights of the paths from i to a in G. Now we observe that

$$p_{ia} = \sum_{j \in N(i)} x_{ij} p_{ja}.$$

To see this, notice that the left hand side enumerates all paths from i to a, and the right hand side enumerates the same paths by grouping them according to the first vertex j that they visit after i. Therefore  $(p_{1a}, \ldots, p_{na})$ , the ath row of our representation Y of L(G, A), is in the nullspace of X. Since each row of Y is in the nullspace of X, rowspace $(Y) \subseteq$  nullspace(X). But

$$\dim(\operatorname{rowspace}(Y)) = \operatorname{rank}(L(G, A)) = n - r, \text{ and}$$
  
$$\dim(\operatorname{nullspace}(X)) = n - \dim(\operatorname{rowspace}(X)) = n - \operatorname{rank}(M[H]) = n - r,$$

so in fact these two subspaces are equal. It follows that rowspace(X) and rowspace(Y) are orthogonal complements. This completes our proof of Theorem 1.  $\Box$ 

### 4

For more information on matroid theory, Oxley's book [8] is a wonderful place to start. The representation of transversal matroids shown here is due to Mirsky and Perfect [7]. The representation of strict gammoids that we use was constructed by Mason [6] and further explained by Lindström.<sup>5</sup>[5]

This note is a small side project of [1]. While studying the combinatorics of generic flag arrangements and its implications on the Schubert calculus, we became interested in

<sup>&</sup>lt;sup>5</sup>It is in this context that he discovered what is now commonly known as the Lindström-Gessel-Viennot theorem [2]. This theorem was also discovered and used earlier by Karlin and MacGregor [4].

the strict gammoid of Example 2 and its representations; we proved that it is the matroid of the arrangement of lines determined by intersecting three generic complete flags in  $\mathbb{C}^3$ . Similarly, the analogous strict gammoid in a triangular array of size n is the matroid of the line arrangement determined by three generic flags in  $\mathbb{C}^n$ .

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